

# Segmentation of the optic nerve head driven by disc divergence and gradient boosting

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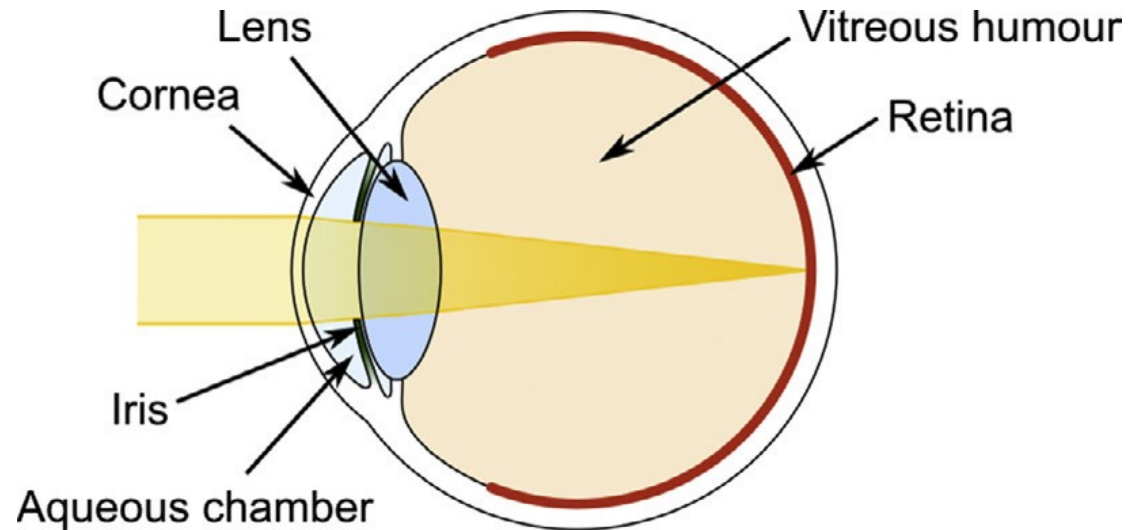
Computer  
Graphics  
Charles  
University

# Motivation

- Availability of medical images
- Slow manual examination
- Need for fast automatic methods
- Eye diseases
  - Glaucoma

# Retinal imaging

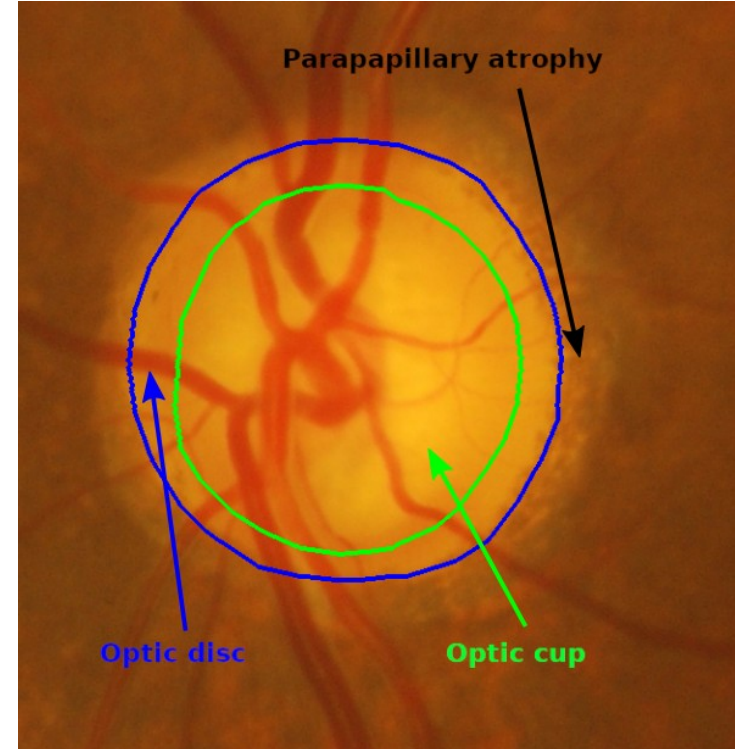
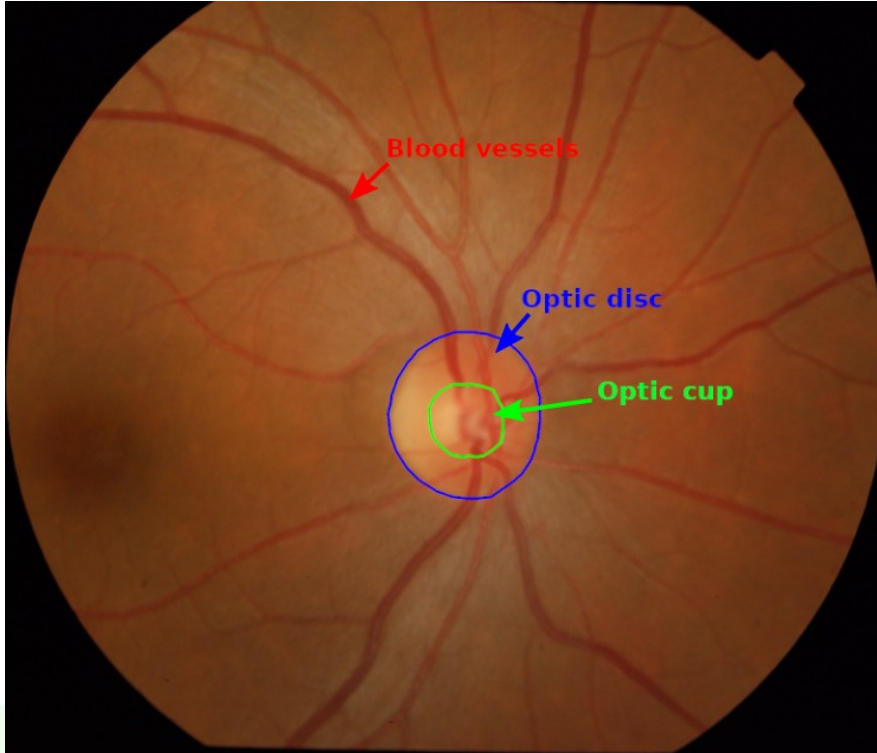
- Fundus camera
- OCT (Optical Coherence Tomography)
- Reconstruction
- Imaging artefacts



The human eye as an optical system.

*Trucco E MacGillivray T Xu Y. Computational Retinal Image Analysis : Tools Applications and Perspectives. London United Kingdom: Academic Press; 2019*

# Optic nerve head



# Related work

Major survey articles [Almazroa et al. 2015][Thakur et al. 2018]

## Retinal image preprocessing

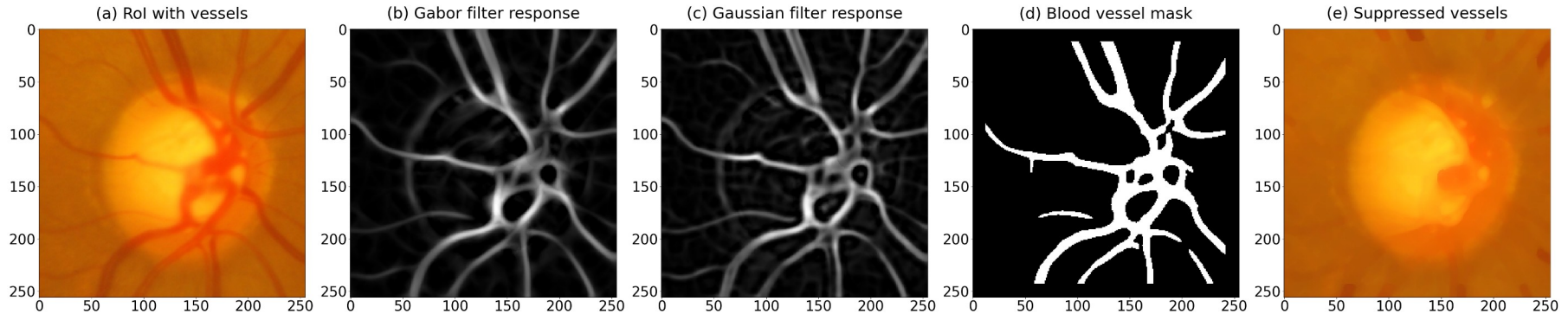
- Region of interest detection [Liu et al. 2008]
- Blood vessel segmentation and inpainting [Khan et al. 2019]

## ONH segmentation techniques

- Thresholding [Ashish et al. 2015]
- Unsupervised clustering
- Active contour and level set methods
- Superpixel classification [Cheng et al. 2013]
- Convolutional neural networks [Panda et al. 2021][Zhang et al. 2021]

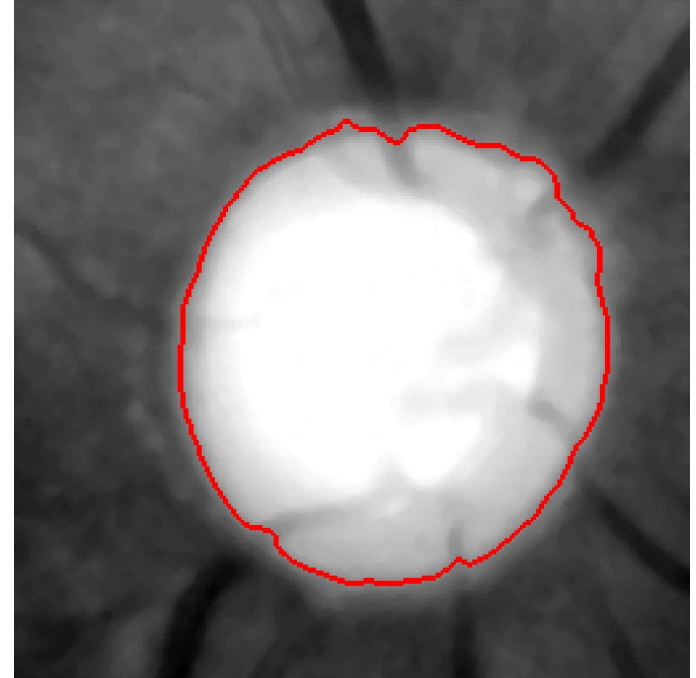
# Retinal image preprocessing

- Region of interest constructed around the highest response after convolution with peak-seeking kernel
- Blood vessel extraction by filter matching



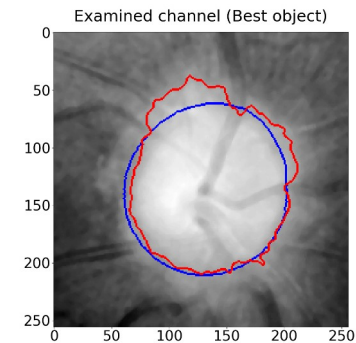
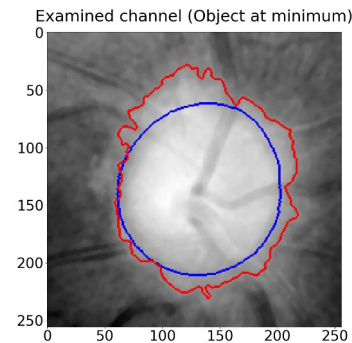
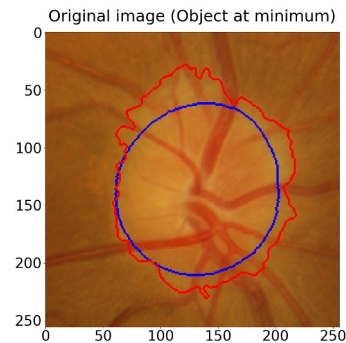
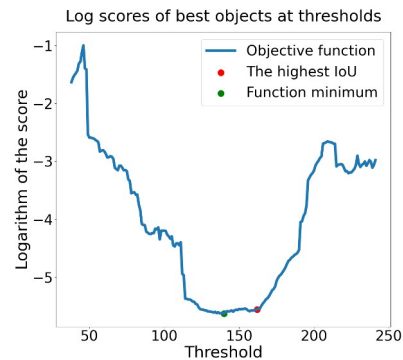
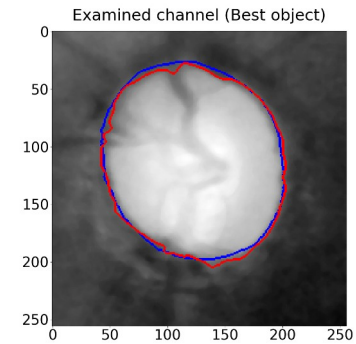
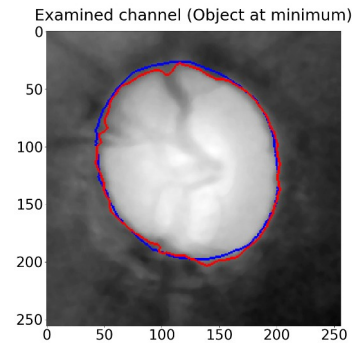
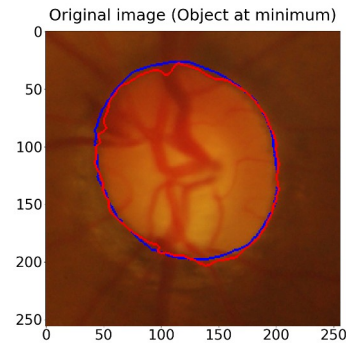
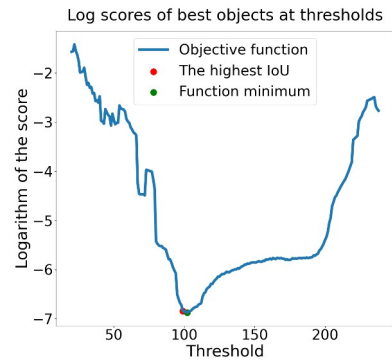
# Disc divergence

- Formula  $\epsilon = \phi \nu \delta \lambda$
- $\phi$  – ellipse divergence
- $\nu$  – vessel coverage
- $\delta$  – contrast with neighbourhood
- $\lambda$  – ROI intersection penalisation



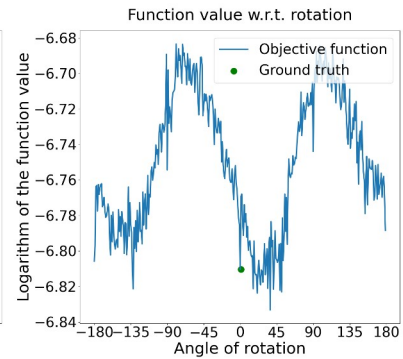
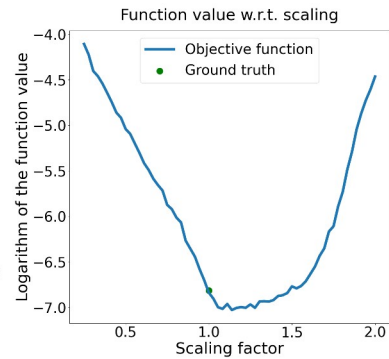
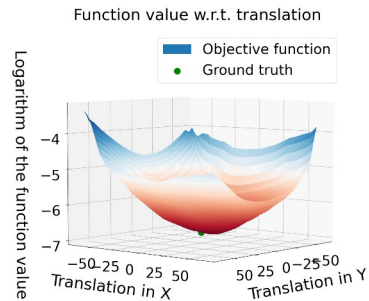
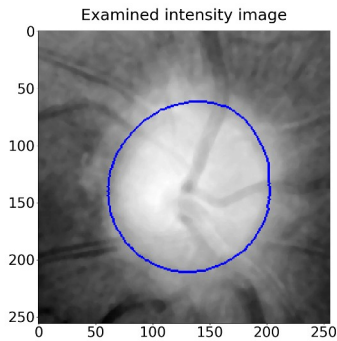
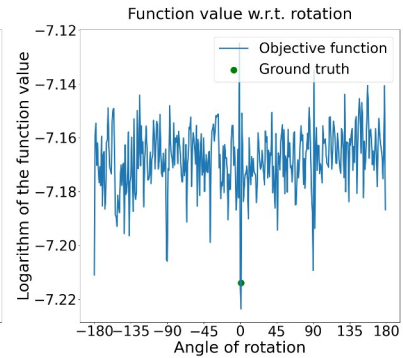
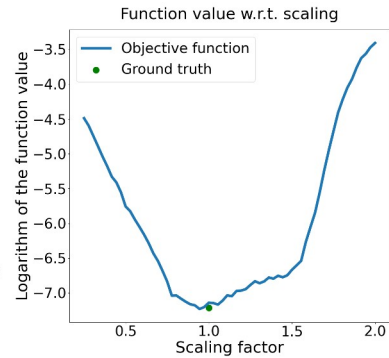
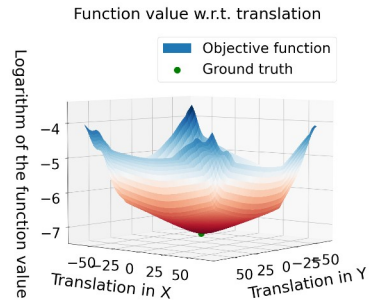
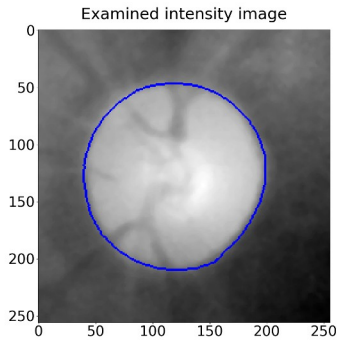


# Disc divergence optimisation

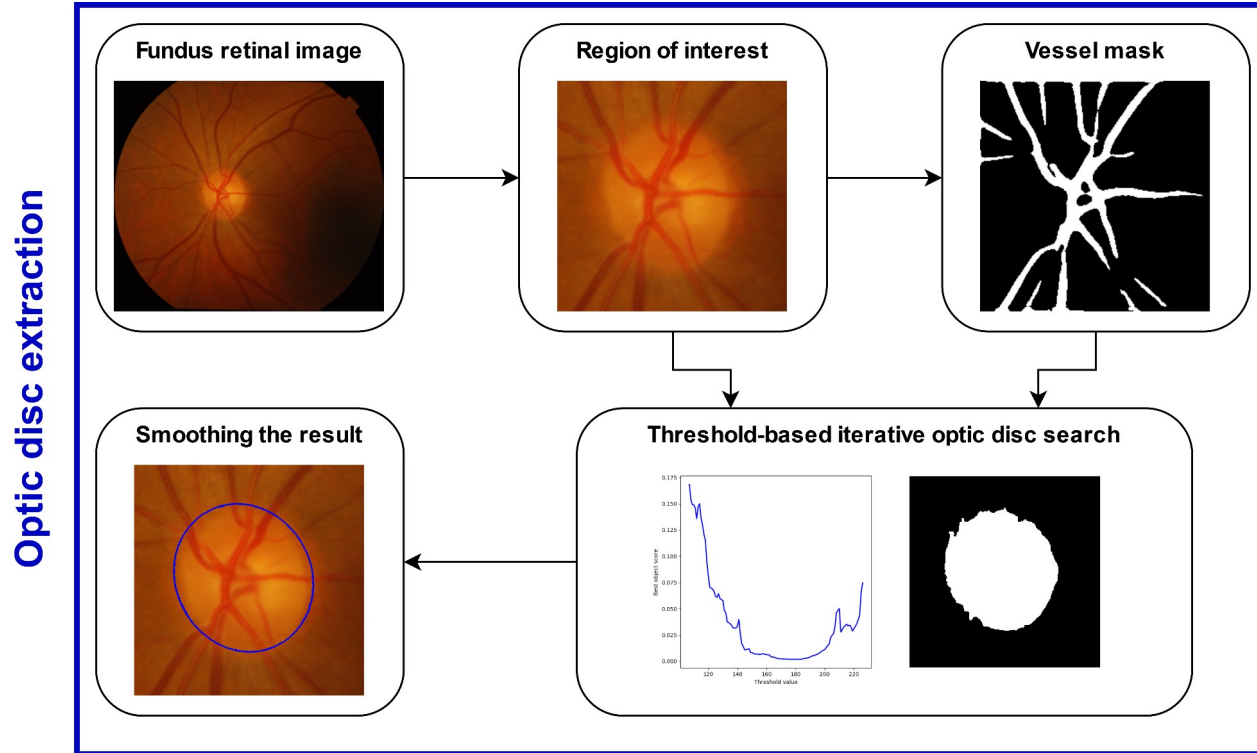




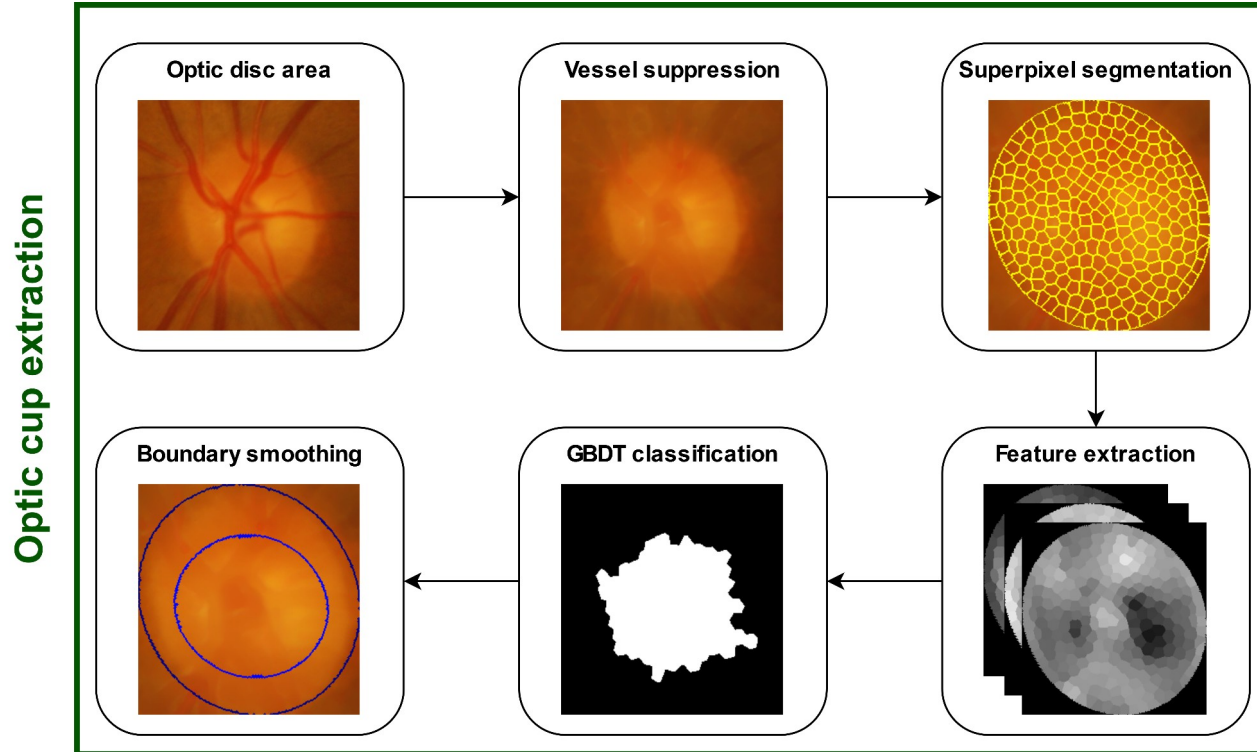
# Ground truth divergence



# Optic disc segmentation

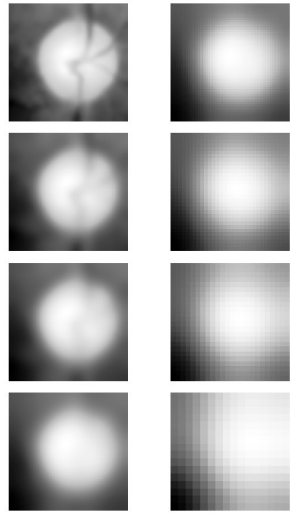


# Optic cup segmentation

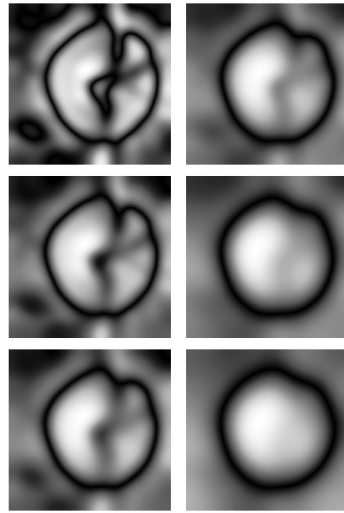


# Superspixel features

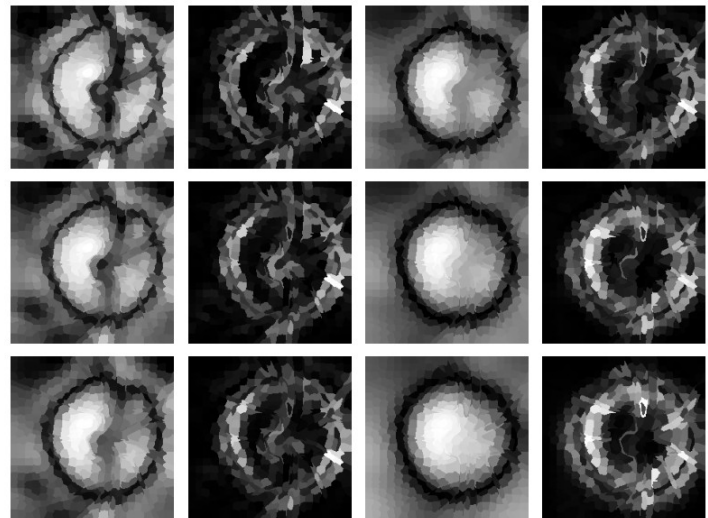
- Mean/variance in colour channels: RGB, HSV, L\*a\*b\*
- Left/right eye estimation, distance from the optic centre or vessel cluster, Centre surround statistics



Gaussian pyramid



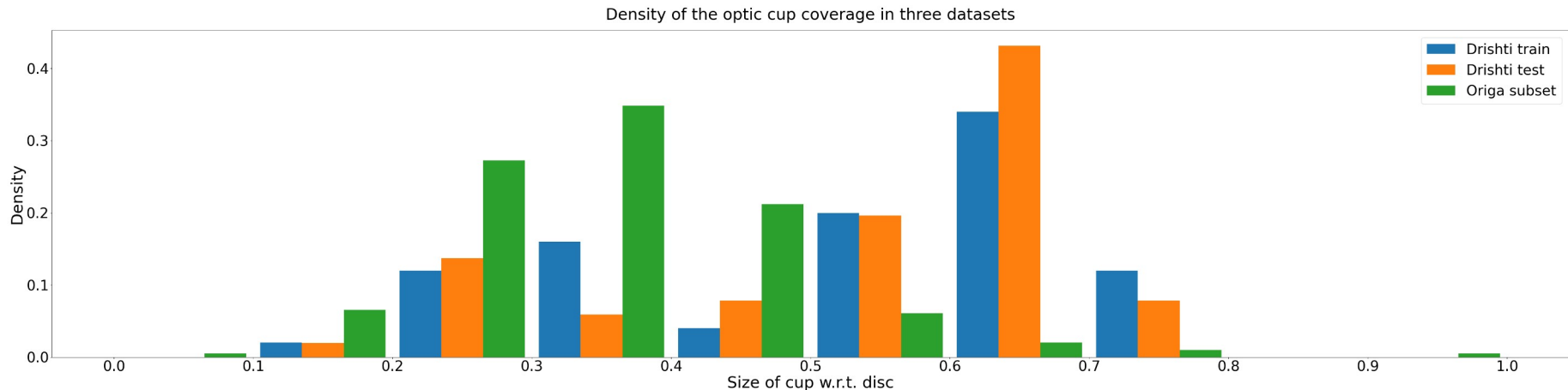
Pyramid level differences



Centre surround statistics (mean/variance)

# Data augmentation

- Balanced selection of superpixels (cup/neuroretinal rim)
- Random transformations (mirror/rotation)
- Imbalanced dataset – varying number of transformations



# Gradient boosting

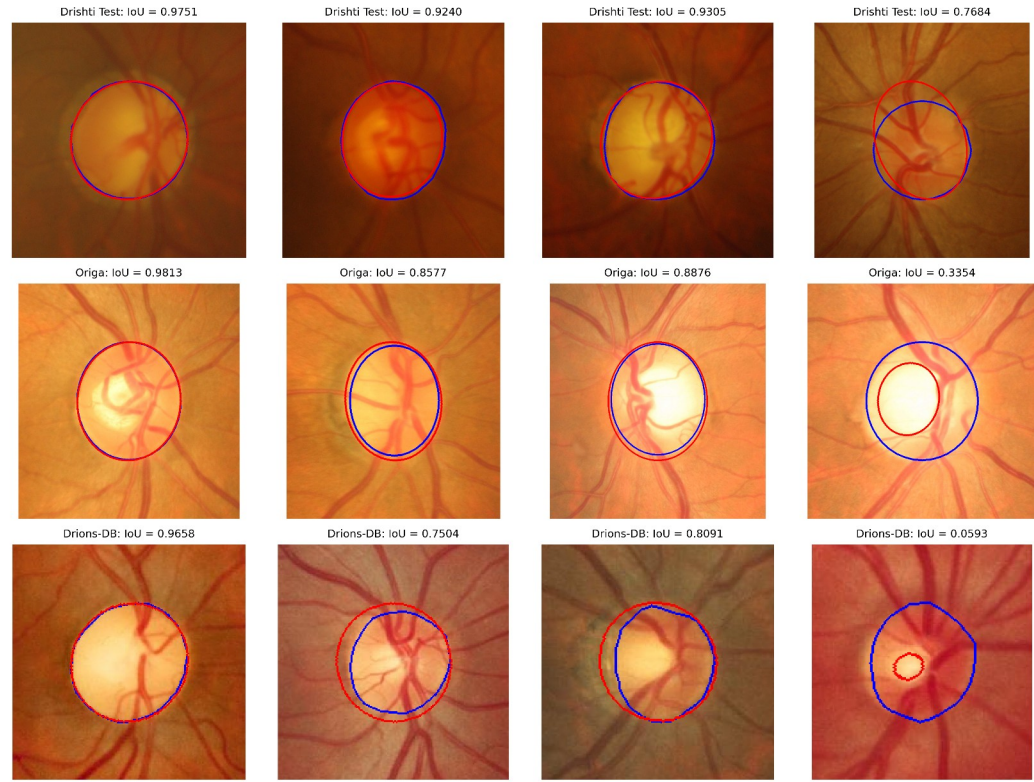
- Gradient boosted decision trees (GBDT)
- Superpixel classification – traditionally SVM

Training	Drishti		Origa	
Testing	Drishti	Origa	Drishti	Origa
GBDT	<b>0.7858</b>	0.5986	<b>0.6513</b>	0.7236
SVM RBF	0.7356	0.5895	0.6500	0.7060
SVM Linear	0.7401	0.5902	0.6328	0.7098
Random Forest	0.7726	<b>0.6027</b>	0.6274	<b>0.7240</b>



# Results (Disc segmentation)

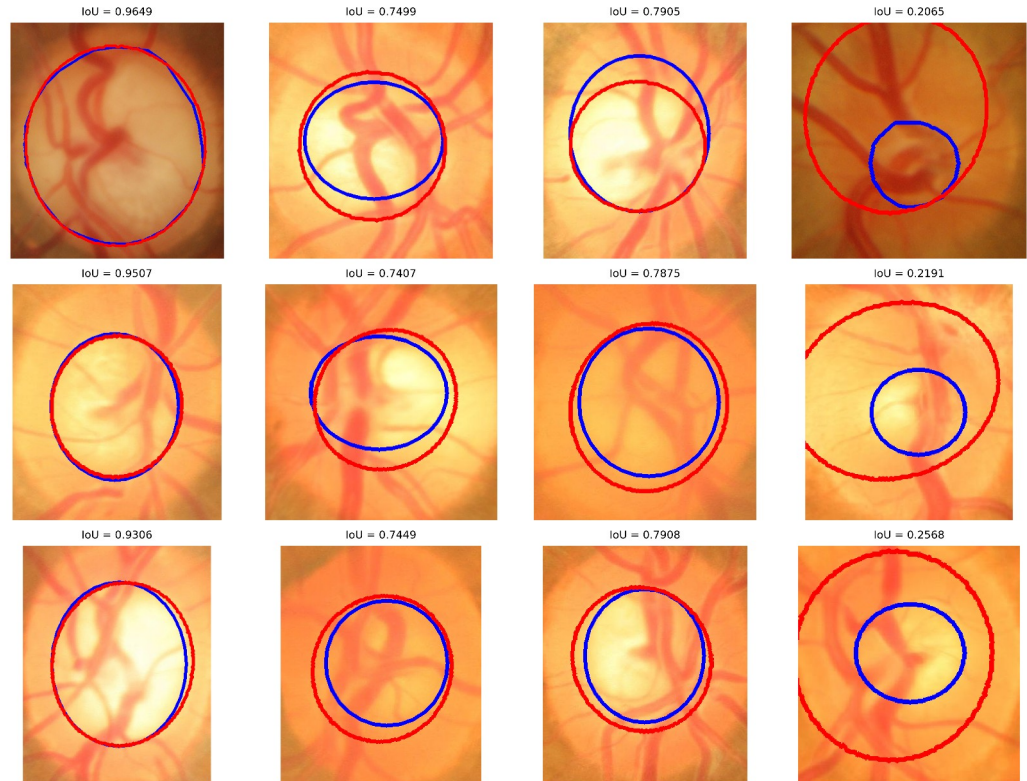
- Blue – ground truth
- Red – segmentation
- Rows from the top:
  - Drishti GS1
  - Origa
  - Drions-DB
- Columns from the left:
  - The best result
  - The mean result
  - The median result
  - The worst result





# Results (Cup segmentation)

- Blue – ground truth
- Red – segmentation
- Drishti and Origa images
- Columns from the left:
  - The best results
  - The mean results
  - The median results
  - The worst results



# References

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Thank you for listening